

EH 88 PE / PET

THROUGH HOLLOW SHAFT INCREMENTAL ENCODER

MAIN FEATURES

Cost effective encoder for asynchronous motors, suitable for elevators and stage machinery.

- · 3 channel encoder (A / B / Z) up to 2500 ppr
- · Power supply up to +28 V DC with several electrical interfaces available
- · Up to 105 kHz output frequency
- · Cable output, connectors available on cable end
- · Sturdy mechanic
- · Up to 40 mm bore diameter
- · Shaft fixing by collar clamping







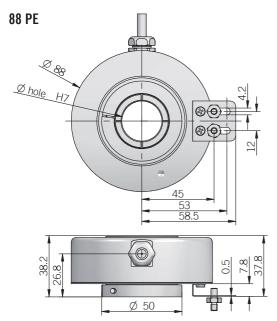


ORDERING CODE	EH 88	BPE 1024	S	5/28	P	30	X	3	PR	. XXX
increm through hollov through hollow	SERIES ental encoder series EH MOI w shaft with torque stop slot 8/ shaft for torque arm fixing 88 ase refer to Accessories for torque ppr fron	DDEL 88PE 8PET e arm Im 500 to 2500 ailable pulses list ZER without zero	O PULSE O pulse S O pulse Z POWER I interface) 5 28 V ELEC	SUPPLY 5 V DC 5 DC 5/28 TRICAL IN PU:	TERFACE sh-pull P e driver L S-422 RS BORE D (mod. PE (mod. PE (mod. PE	IAMETER mm 25 mm 30 c) mm 35 c) mm 38 c) mm 40 NCLOSURI	E RATING IP 54 X X ROTATIO 30	N SPEED 00 rpm 3	PUT TYPE	. XXX
		preferred ca	able lengths	3 1,5 / 2 / 3	/ 5 / 10 m,				. PR5)	VARIANT

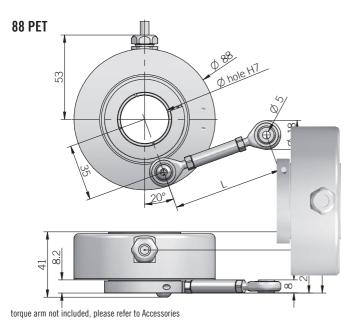




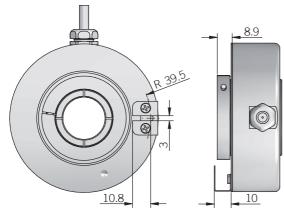




for torque pin please refer to Accessories



OPTIONAL TORQUE STOP SLOT



for torque stop slot and torque pin please refer to Accessories

recommended mating shaft tolerance g6 dimensions in mm

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Resolution	from 500 to 2500 ppr	
Power supply ¹	$ 5 = 4,5 \dots 5,5 \text{ V DC} $ $5/28 = 4,5 \dots 30 \text{ V DC (reverse polarity protection)} $	
Power draw without load	I 800 mW	
Max load current	20 mA / channel	
Electrical interface ²	push-pull / line driver HTL (AEIC-7272) line driver RS-422 (AELT-5000 or similar)	
Max output frequency	105 kHz	
 Counting direction 	tion A leads B clockwise (shaft view)	
Electromagnetic compatibility	according to 2014/30/EU directive	
RoHS	RoHS according to 2011/65/EU directive	
UL / CSA	certificate n. E212495	

MECHANICAL SPECIFICATIONS

	mediminate of Edit formation			
)	Bore diameter	Bore diameter Ø 25 / 30 / 35 / 38 / 40 mm		
Enclosure rating		IP 54 (IEC 60529)		
Max rotation speed		3000 rpm		
Shock		50 G, 11 ms (IEC 60068-2-27)		
Vibration		10 G, 10 2000 Hz (IEC 60068-2-6)		
Moment of inertia		45 x 10 ⁻⁶ kgm² (10,68 x 10 ⁻⁴ lbft²)		
Starting torque (at +20°C / +68°F)		< 0,02 Nm (2,83 Ozin)		
Bearing stage material Shaft material		EN-AW 2011 aluminum		
		up to ø 38 mm: EN-AW 2011 aluminum ø 40 mm: 1.4305/AISI 303 stainless steel		
Housing material		EN-AW 2011 aluminum		
Bearings		n.2 ball bearings		
Bearings life		10 ⁹ revolutions		
Operating/temperature ^{3, 4}		-30° +85°C (-22° +185°F)		
Storage temperature		-30° +85°C (-22° +185°F)		
Weight		350 g (12,35 oz)		

as measured at the transducer without cable influences

RESOLUTIONS

500 - 512 - 720 - **1000** - **1024** - 1440 - 2500

please directly contact our offices for other pulses, preferred resolutions in bold

CONNECTIONS							
Function		Cable P	Cable L / RS				
+V DC		red	red				
0 V	1	black	black				
(A+	})	green	green				
A-	11	/	brown or grey				
B+	2	yellow	yellow				
B-		1	orange				
Z+		blue	blue				
Z-		/	white				
<u>+</u>		shield	shield				





² for further details refer to OUTPUT LEVELS on TECHNICAL BASICS section

³ measured on the transducer flange ⁴ condensation not allowed