



## **MAIN FEATURES**

 $\emptyset$  120 mm through hollow shaft encoder designed for medium / big size motors.

- $\cdot$  3 channel encoder (A / B / Z) up to 2048 ppr
- · Power supply up to +24 V DC with several electrical interfaces available
- · Up to 105 kHz output frequency
- · Cable output, connectors available on cable end
- Through hollow shaft diameter up to 60 mm
- · Shaft fixing by grub screws





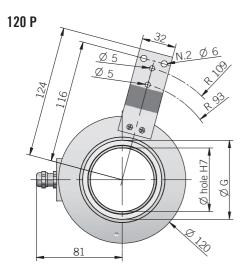


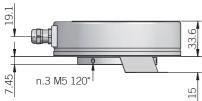


ORDERING CODE	EL	120P	1024	S	5/28	P	50	X	3	PR	. XXX
	SERIES										
	incremental encoder series EL	MODEL									
	through hollow shaft with spi										
			OLUTION								
	PF refer to th	or from 400 e available	pulses list								
			ZEI	O PULSE							
		V	without zei with zei	o pulse S o pulse Z							
			With 201		SUPPLY						
	(w	wit) ith L electric		al interface)							
	(w	IIII L EIEGIII	sai iliterrati		DC 5/28						
					TRICAL IN						
				IN	PN open c pu	sh-pull P					
					lin	e driver L					
						ROKE D	mm 40				
							mm 50				
							mm 60 ENCLOSUR				
						•		IP 54 X			
							MA	X ROTATIO 300	N SPEED 00 rpm 3		
							radiala	oblo (stand		PUT TYPE	
			preferred o	able length	s 1,5 / 2 / 3	/5/10 m,		able (stand I after OUTPl			
											VARIAN
									(	custom ver	sion XX







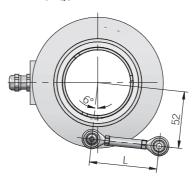


recommended mating shaft tolerance g6

dimensions in mm					
ELECTRICAL SPECIFICATIONS					
Resolution	from 400 to 2048 ppr				
Power supply <sup>1</sup>	5 = 4,5 5,5 V DC 5/28 = 4,75 29,4 V DC 8/24 = 7,6 25,2 V DC (reverse polarity protection)				
Current consumption without load	100 mA max				
Max load current	C / P = 50 mA / channel L = 20 mA / channel				
Electrical interface <sup>2</sup>	NPN open collector (pullup max +30V DC) push-pull / line driver HTL (AEIC-7272) line driver RS-422 (AELT-5000 or similar)				
Max output frequency	105 kHz				
Counting direction	A leads B clockwise (shaft view)				
Electromagnetic compatibility	according to 2014/30/EU directive				
RoHs	according to 2011/65/EU directive				
UL / CSA	certificate n. E212495				

CONNECTIONS					
Function	Cable C / P	Cable L			
+V DC	red	red			
0 V	black	black			
A+	green	green			
A-	/	brown or grey			
B+	yellow	yellow			
В-	/	orange			
Z+	blue	blue			
Z-	/	white			
<u></u>	shield	shield			

## WITH TORQUE ARM





or	torque	arm	please	refer to	Accessories
O.	torquo	uiiii	picaso	10101 10	1100000001100

SHAFT DIAMETER	G
ø 40	ø 65
ø 50	ø 65
ø 60	ø 75

MECHANICAL SPECIFICATIONS				
Bore diameter	ø 40 / 50 / 60 mm			
Enclosure rating	IP 54 (IEC 60529)			
Max rotation speed	3000 rpm			
Shock	50 G, 11 ms (IEC 60068-2-27)			
Vibration	10 G, 10 2000 Hz (IEC 60068-2-6)			
Moment of inertia	approx 215 x 10 <sup>-6</sup> kgm <sup>2</sup> (51 x 10 <sup>-4</sup> lbft <sup>2</sup> )			
Starting torque (at +20°C / +68°F)	< 0,05 Nm (7 Ozin)			
Bearing stage material	EN-AW 2011 aluminum			
Shaft material	EN-AW 2011 aluminum			
Housing material	EN-AW 2011 aluminum			
Bearings	n.2 ball bearings			
Bearings life	10 <sup>9</sup> revolutions			
Operating temperature <sup>3, 4</sup>	0° +60 °C (+32° +140°F)			
Storage temperature <sup>4</sup>	-25° +70 °C (-13° +158°F)			
Weight	750 g (26,46 oz)			

<sup>&</sup>lt;sup>1</sup> as measured at the transducer without cable influences

## **RESOLUTIONS**

**400** - 800 - 1000 - **1024** - 1440 - 1600 - 2000 - **2048** 

please directly contact our offices for other pulses, preferred resolutions in bold



 $<sup>^{\</sup>rm 2}$  for further details refer to OUTPUT LEVELS on TECHNICAL BASICS section

<sup>&</sup>lt;sup>3</sup> measured on the transducer flange

<sup>4</sup> condensation not allowed